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path,  $T_v = 2LV^2/(wO - wI)$ , is obviously shorter than the time along the path ...

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4 Goldstein 8.26 4.1 Part (a) In the given configuration, both springs elongate or compress by the same magnitude. Suppose  $q$  denotes the position of the mass

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from the left end. At  $t = 0$ ,  $q(0) = a = 2$ , but the unstretched lengths of both springs are given to be zero. Therefore, the elongation (compression) of spring  $k_1$  is  $q$  and the compression (elongation) of spring  $k_2$  is  $q$ . The potential energy ...

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Goldstein Chapter 1 Derivations Michael Good June 27, 2004 1 Derivations 1. Show that for a single particle

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with constant mass the equation of motion implies the following differential equation for the kinetic energy:  $\frac{dT}{dt} = F \cdot v$  while if the mass varies with time the corresponding equation is  $\frac{d(mT)}{dt} = F \cdot p$ . Answer:  $\frac{dT}{dt} = \frac{d(\frac{1}{2}mv^2)}{dt} = mv \cdot v' = ma \cdot v = F \cdot v$  with time variable mass,  $\frac{d}{dt} \dots$

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The constraint that the mass is on the wedge is  $r = R + l(\cos \theta, \sin \theta)$ , or  $x = X + l \cos \theta$  and  $y = l \sin \theta$  where  $l$  is the distance the mass traveled down the wedge. This is one constraint, which we can express as a function of  $x, y, X$  as  $f = (x - X) \sin \theta - y \cos \theta = 0$ .

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